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ijerst.editor@gmail.com
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Research Paper**AN EXPLAINABLE ARTIFICIAL INTELLIGENCE-ENABLED BIM-CENTRIC DIGITAL TWIN FRAMEWORK FOR REAL-TIME CONSTRUCTION MONITORING****Dr. Eeman Emhemed Ben Omran**

Department of Civil Engineering,

Higher Institute of Science and Technology – Sawkna- Al jufrah-Libya

Highlights of the Study

- Proposed an Explainable AI-enabled BIM-centric Digital Twin framework for real-time construction monitoring and intelligent project supervision.
- Integrated BIM, IoT, and GIS data streams to create a synchronized, data-driven virtual replica of on-site construction activities.
- Enhanced predictive decision-making by embedding AI-based progress, safety, and risk analytics within the digital twin environment.
- Improved transparency and stakeholder trust through explainable decision interpretation, enabling accountable and regulation-compliant construction management.

Abstract

The construction industry has been rapidly digitalized, and thus, the process of the use of Building Information Modelling (BIM) and Digital Twin technology has increased in the number of projects being monitored and controlled. Nevertheless, traditional instances of digital twins can be described as visualization platforms that have a short analytical intelligence and lack decision transparency. This paper presents an Explainable Artificial Intelligence-powered BIM- based Digital Twin system of real-time construction monitoring. The scheme combines input data of multi-source construction, such as site progress, IoT sensor feeds, and scheduling in a synchronized digital twin environment. There is a predictive analytics engine built on AI, which predicts delays, safety issues, and productivity variability, as well as an explainable decision interpretation that increases the transparency of the autopilot analysis and recommendations. It is also backed by interactive visualization and decision support interface to help the project stakeholders in proactive planning and mitigation of risks. The results of implementation indicate that there are better monitoring accuracies, quick site dynamics, and increased interpretability in project control procedures. The paper confirms that incorporateability of explainable intelligence into digital twins, generated through BIM, can enhance data-based decision-making, responsibility and operational performance of complex civil infrastructure developments to a large extent.

Keywords: BIM (Building Information Modelling), Construction Monitoring, Digital Twin, Explainable Artificial Intelligence (XAI), Predictive Analytics

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1. Introduction

The construction industry is a very important part of the economic development but it still experiences chronic problems of delaying of the projects, overspending on the projects, and lack of real time monitoring of the projects[1]. Conventional construction monitoring has relied extensively on manual on-site inspection, periodic reportage, and disjointed communication between the stakeholders, and as such may lead to slow responses to arising problems[2]. The Building Information Modeling (BIM) has become very

popular in recent years as a digital platform that enables the project planning, coordination, and visualization[3]. Though BIM has greatly enhanced the integration of design and preconstruction decision-making, its use at the construction stage is usually restricted to the static images of the proposal conditions[4]. To fill this gap, the digital twins concept has been implemented in the construction sphere where it seeks to develop a dynamic and constantly refreshed digital image of physical construction operations[5]. Connections between site-level data and BIM models make

digital twins offer a chance to conduct real-time monitoring, enhanced situation awareness, and make better decisions when implementing construction activities[6].

An increasing number of researches have been conducted on BIM-based construction monitoring and the use of digital twin technologies to improve the performance of construction[7]. A set of available research revealed the possibilities of combining BIM with sensing devices, automated systems of data collection, and analysis tools to monitor the state of construction and the presence of deviations against the scheduled plans[8]. Implementation of digital twins has also facilitated real-time alignment of physical construction of a construction and its digital model, facilitating analysis of performance and predictive analysis[9]. Nevertheless, there are some shortcomings even though these advancements have been made[10]. Most of the available methods build on complicated data-processing pipelines that can hardly be understood by practitioners, which restrict the ability to be useful in construction sites. Moreover, the existing systems tend to pay much attention to data visualization instead of explaining the reasons of deviations, as well as, their effects on construction outcomes. The inability to be transparent with decision-support mechanisms and the disjointed aggregation of monitoring tools limit the ubiquitous implementation of digital twins technologies in actual construction projects.

To address these issues, this paper suggests an elucidatable artificial intelligence-based, BIM-driven digital twin model of real-time construction monitoring. The suggested framework will assist construction engineers by converting real-time data at the site into easily understandable information that is in line with the construction processes and decision-making. The framework does not give priority to the complex algorithms, but instead concentrates on the implementation of BIM models, site monitoring data, and understandable decision-support logic to make them more transparent and usable. A typical example of a building construction is presented to show how the proposed approach can be applicable, namely, its capability to help observe the progress deviation in time and enhance the efficiency of monitoring during the construction process. Through its emphasis on interpretability and practical application, this paper has provided a well-organized, engineer-gear framework to further

enhance the use of digital twins in construction to facilitate more efficient, reliable, and open-minded real-time construction monitoring.

1.1 Problem Statement and Research Motivation

The issue of real-time monitoring during the construction phase of the project is still a lingering problem in civil engineering practice despite the constant development of construction technologies. Construction business is marked by the dynamic site conditions, various types of activities that depend upon each other, and numerous deviations of the planned schedule and resources distributions. The traditional monitoring strategies are mainly based on manual checks, regular progress reports, and subjective evaluations, which are not always able to reflect the actual site situation. Consequently, the delays, re-work, and poor resource use have often been discovered too late after the effects they have had on the projects performance. This fact is due to the lack of timely and reliable monitoring mechanisms that would enable the project managers and the site engineers to take action in advance in case of arising construction issues.

Despite the fact that Building Information Modeling (BIM) has enhanced planning and coordination in building construction activities, its utilization in the execution stage is usually limited to fixed models of intended designs and schedules. Likewise, there have been recent projects of digital twins that have tried to bridge the gap between physical construction processes and digital models through the introduction of sensor data and automated tracking systems. Nevertheless, much of the current deployment of digital twins focuses on data gathering and visualization, instead of taking action on the decision-support side. As a matter of fact, the professionals in the construction business are usually introduced to vast amounts of data but without clear descriptions of how deviations develop and what should be done to rectify them. This uninterpretability undermines the use of digital systems and their implementation at the construction site, as an immediate decision must be made, and accessible and engineering-applicable information is required.

The study is motivated by the fact that there is a gap between advanced digital monitoring technology and real construction decision-making. It is evident that there is a need to have monitoring frameworks that are able to not only offer real-time

updates but also decode the complex construction data into comprehensible information to engineers and managers. The explainable artificial intelligence is an option that can be used to increase the transparency level, as it allows providing the reasoning of detected deviations and performance evaluations instead of using opaque or black-box models. With the integration of explainable decision-support systems into a BIM-focused digital twin setting, construction stakeholders can have a better situational awareness and be more assured in the results of digital monitoring. The research is hence driven by the aim of making a practical, interpretable and construction-based framework which helps to monitor in real-time and to make informed decisions on the execution stage of the civil engineering projects.

1.2 Research Significance

The importance of the study is that it has aided the enhancement of construction-phase monitoring by providing a practical and understandable digital framework that fits civil engineering applications. Although the main approach to digitalization in the construction industry has been on the design coordination and data visualization, there is an urgent need to have monitoring systems that will be used to make quality decisions in real-time and transparent when a project is being executed. The proposed research will meet this requirement by highlighting a BIM-focused digital twin solution that is closely related to construction processes and engineering processes. By means of situational awareness development, the proposed framework allows improving the real-time monitoring and facilitating the active control of construction operations, minimizing the chances of delays, inefficiencies, and unforeseen interventions.

One of the most important points about the relevance of the study is the incorporation of explainable decision-support mechanisms into the digital twin setting. In contrast to traditional data-driven systems that in many cases become black boxes, the proposed method is more interpretable, which allows the engineer and project managers to know the reasons behind the observed deviations and performance changes. This openness is especially pertinent in the construction field where decisions have to be supported by engineering judgment and reality limitations. Moreover, the framework is crafted to accommodate normal building construction projects, and thus it is

applicable to most of the civil engineering applications. The research will help to improve the efficient, reliable, and engineer-focused digital twins in the construction industry by linking the significant digital technologies with the construction monitoring in the real world.

1.3 Key Contributions of the Study

- A BIM-centric digital twin framework for real-time construction monitoring during the execution phase was developed, enabling continuous alignment between planned construction models and actual site conditions.
- An explainable decision-support mechanism was integrated into the digital twin environment to provide transparent and interpretable insights into construction progress deviations and site performance.
- A structured approach for synchronizing construction planning data with real-time site information was established, supporting improved situational awareness and monitoring efficiency.
- The practical applicability of the proposed framework was demonstrated through a representative building construction case, illustrating its effectiveness in identifying schedule deviations in a timely manner.
- The study contributed an execution-oriented digital monitoring framework that enhanced the usability and reliability of digital twin applications for civil engineering construction practice.

2. RELATED WORK

2.1 BIM-Based Construction Monitoring

The Building Information Modeling (BIM) is a technology based on the improvement of construction monitoring because it allows digital representation of planned construction activities and comparison with the actual progress on site. Recent research has been aimed at mitigating the need to use manual inspection which is subject to error and time consuming as well as temporal resolution. Vassena et al.[11] came up with a digital progress monitoring model, which combines 4D BIM scheduling software and indoor mobile mapping software to automated the comparison of as-intended and as-constructed construction conditions. The work showed that digital progress monitoring can be applied successfully in the real construction settings by connecting point clouds information and BIM objects with a tailored work

breakdown structure. Nevertheless, the issue of data alignment accuracy and survey reliability were pointed out, which means that stronger integration strategies should be implemented.

In order to overcome the issue of disaggregated data reporting and sluggish decision-making, Radman et al. [12] proposed a QR-enabled real-time monitoring system based on the integration of BIM, mobile data capture, cloud databases, and business intelligence dashboards. In their comparative case study, continuous data integration was indeed seen to have much higher schedule reliability and forecasting accuracy than traditional tracking methods. Although these are advantages, the effectiveness of the framework relies on the sustained adoption of QR and organizational readiness to go digital, which can restrict the scalability of different project settings.

BIM monitoring that is based on visual data has also received interest. Zhang et al.[13] have come up with a semantic segmentation-based progress monitoring model to concrete construction, which incorporates attention mechanisms into an end-to-end deep learning model that enhances accuracy in harsh site conditions. Their findings indicated that they were very precise in automated progress evaluation, and early productivity problems can be detected. However, the method is also vulnerable to the environmental factors like light and positioning of cameras, which point to the shortcoming of methods of monitoring that rely on sight.

In addition to construction implementation, BIM-based systems have been used to facilitate the interdisciplinary teamwork. To compare the collaboration design in concurrent and sequential design, Chen et al. [14] explored cloud-based BIM environments. Their results indicated that sharing of information on a real-time basis enhances coordination and early detection of issues but it also raises cognitive load and necessitates effective coordination processes. On the same note, BIM monitoring through AR has been discussed to increase awareness of space on site. Bikandi-Noya et al.[15] suggested a drift correction method in BIM-related systems to enhance the accuracy of localization in augmented reality systems. Although the method contributed greatly to minimizing alignment errors, the performance of the method relies on proper plane identification and quality BIM models. All of these research works show the potential of BIM in construction monitoring and unveil certain challenges that are

still faced in terms of accuracy, interoperability, and real-time reliability.

2.2 Digital Twin Applications in Construction

Digital twin technology builds upon the BIM by allowing the ongoing synchronization of the physical processes of construction and their digital counterparts. In contrast to stationary BIM models, digital twins also strive to capture real-time circumstances and help to make adaptive decisions during the project life cycle. Chacon et al.'s [16] information pipelines provide links between live construction information streams to a central digital twin, allowing the monitoring to be integrated using dashboards. Their case study indicated that they had better situational awareness, management insight, but still the data heterogeneity and integration complexity are major challenges to scalability.

Digital twin frameworks that are more advanced have attempted to include predictive and adaptive control schemes. Khoshkonesh et al.[17] suggested a 4D/5D digital twin framework through a combination of BIM with computer vision, probabilistic scheduling, and reinforcement learning to control the dynamic costs and schedule. The framework was implemented in a real project and the accuracy of forecasting was improved and also resource allocation was optimized. Although it was effective, the complexity of the system and the large data volumes to be utilized present a challenge to its mass use in traditional construction settings.

Digital twins have also been implemented in other areas of use outside of construction execution, such as facility and asset management. Siv[18] introduced scalable digital twin architecture of smart campus management, which combines the use of laser scanning, enriched BIM, and IoT-powered dashboards. The solution proved to be better in terms of asset documentation and maintenance planning, but it used simulated sensor data, which highlights the importance of real-time data validation in operational environment.

Although some studies focus on the intersection of BIM and digital twin technology, there are still unsolved problems. According to Gray et al.,[19] despite the complexity of the geometric and semantic information offered by BIM, digital twins demand constant streams of data, standard integration protocols, and lifecycle-based intelligence. The non-existence of shared standards and interoperable frameworks constrains the reality

of the use of full functional construction digital twins. These results prove that the idea of digital twins is still rather perspective, and its successful application to the process of real-time monitoring of the construction is not complete.

2.3 AI-Assisted Construction Monitoring

Construction monitoring systems have been exposed to artificial intelligence in order to automate the process of progress assessment, detection of anomalies, and prediction of performances. Deep learning approaches based on the use of vision are especially common because they can be used to identify meaningful information in site images and videos. Chua and Cheah[20] introduced a window based visual monitoring system in prefabricated building, which involves the use of object detectors and reasoning based modules to deal with the occlusions and incomplete information. Their strategy enhanced strength over the traditional detectors but depended on facade elements as progress indicators which restricted the application to specific typologies of construction.

Similarly, Ekanayake et al.[21] designed a deep learning-based system on Mask R-CNN to automate monitoring the progress of construction indoors. The model has been tested at various locations and it was found to be a strong generalization tool and has high potential to be deployed to the cloud by using interfaces. Nevertheless, its functionality is still subject to the quality of images and location-specific visual features, which is of concern in a variety of construction settings.

Other than computer vision, AI has also been implemented to comprehend the drivers of technology adoption and performance in automated monitoring systems. Qureshi et al.[22] used the structural equation modeling methodology to determine the determinant technological factors that can lead to effective progress monitoring. Their statistically proven framework could offer important theoretical information but did not focus on the real-time system implementation and related integration with BIM and digital twins.

Most current methods, despite their increasing uses in the monitoring of construction, are black box models despite the increasing use of AI in construction monitoring. The un-explainability will limit the transparency and minimize the level of confidence between the construction professionals who need a result that can be interpreted to aid in

decision-making. The need of explainable AI mechanisms to match the engineering logic and project control practices highlights this gap.

2.4 Limitations of Existing Approaches

Despite the fact that BIM, digital twin, and AI technologies have improved the construction monitoring significantly, their combination is limited by a number of issues. Revolti et al.[23] emphasized that the switching between BIM and digital twin settings is more of a conceptual than operational nature and with few real-life applications and no standardized integration protocols. In a similar manner, the research by Zhou[24] multi-dimensional digital twin framework exhibited high performance increase but demanded a significant nature of infrastructure, availability of data and complexity in the system and it may not be adopted in a normal construction project.

Moreover, Pal et al.[25] highlighted the fact that the digital twin building systems are rather fragmented, covering single-purpose monitoring, but they do not have closed-loop control between the planning, execution, and feedback. The lack of interoperability, poor and inconsistent data quality, and little understanding of AI-based analytics remains an obstacle to smooth real-time monitoring. All these limitations suggest that there is no single, interpretable and BIM-focused digital twin model that will enable the real-time monitoring of the construction process in a practical and scalable way.

2.7 Identified Research Gaps

Although the recent developments in the BIM-based monitoring, digital twin applications, and AI-based construction analytics have made significant strides, there are a number of research gaps that are essential. Current literature concentrates mostly on non-real-time systems or partially synchronized BIM systems without real-time incorporation with dynamic site data. The current digital twin applications tend to be disjointed with a focus on individual project functions without an integrated, execution-based monitoring system. Further, AI-based monitoring solutions are to a great extent black-box systems with little transparency and understandability to the construction practitioners. Lack of explicatory decision support removes trust, useability and realistic implementation at the site level. Moreover, the interoperability issues and absence of unified data fusion strategies do not allow BIM-digital twin to be synchronized

smoothly. These gaps demonstrate the necessity of an explainable, BIM-focused, digital twin framework with the ability to monitor construction in real-time and interpret it.

Table 1. Summary of Related Work on BIM, Digital Twin, and AI-Based Construction Monitoring

Reference	Method / Approach	Advantages	Limitations
Vassena et al. [11]	4D BIM integrated with indoor mobile mapping and point cloud comparison	Automated as-planned vs. as-built progress assessment; reduced manual inspection	Data alignment accuracy issues; survey reliability concerns
Radman et al. [12]	QR-enabled real-time monitoring using BIM, mobile data capture, cloud database, and BI dashboards	Improved schedule reliability; real-time decision support	Dependence on consistent QR usage; limited scalability due to organizational readiness
Zhang et al. [13]	Semantic segmentation-based deep learning framework with attention mechanisms	High accuracy in automated progress monitoring; early productivity issue detection	Sensitive to lighting conditions and camera placement
Chen et al. [14]	Cloud-based BIM platform for concurrent design collaboration	Improved coordination and early issue detection	Increased cognitive workload; requires effective coordination mechanisms
Bikandi-Noya et al. [15]	BIM-aware drift correction for augmented reality-based monitoring	Enhanced localization and alignment accuracy	Performance depends on accurate plane detection and BIM quality
Chacón et al. [16]	Digital twin information pipelines with real-time dashboards	Improved situational awareness and integrated monitoring	Data heterogeneity and integration complexity
Khoshkonesh et al. [17]	4D/5D digital twin combining BIM, computer vision, probabilistic scheduling, and reinforcement learning	Improved forecasting accuracy and optimized resource allocation	High system complexity and substantial data requirements
Siv [18]	Scalable digital twin framework for smart campus asset management	Improved asset documentation and maintenance planning	Reliance on simulated sensor data; lack of real-time validation
Gray et al. [19]	Conceptual analysis of BIM–digital twin convergence	Identified lifecycle intelligence and integration gaps	Lack of standardization and interoperable implementation
Chua & Cheah [20]	Vision-based AI monitoring using object detection and reasoning modules	Robust to occlusions and incomplete data	Limited to façade-based prefabricated construction
Ekanayake et al. [21]	Mask R-CNN-based automated indoor progress monitoring	Strong generalization across multiple sites; cloud deployable	Sensitive to image quality and site-specific visual features
Qureshi et al. [22]	Structural equation modeling for technology adoption analysis	Identified key factors influencing monitoring effectiveness	No real-time system implementation or BIM integration
Revolti et al. [23]	Analysis of BIM-to-digital twin transition	Highlighted operational and standardization gaps	Limited real-world deployment evidence
Zhou [24]	Multi-dimensional digital twin framework	Performance improvements in monitoring	High infrastructure and data requirements
Pal et al. [25]	Review of fragmented digital twin monitoring frameworks	Identified lack of closed-loop control mechanisms	Poor interoperability; limited AI explainability

Table 1 provides a comparative overview of the recent research on BIM-based, digital twin-supported, and AI-assisted construction monitoring. The table also underscores the fundamental methodology employed in each of the references, their main strengths, and the potential shortcomings. Although the current methods are able to achieve remarkable advancements in automation, precision, and decision support, they are usually fraught with the problems of data integration intricacy, scalability, environmental attentiveness, and low explanations. This analogy shows clearly the necessity of unified, interpretable, and BIM-centric digital twin framework of construction monitoring in real time.

3. Proposed BIM-Centric Digital Twin Framework and System Architecture

The BIM-based digital twin system suggested can be conceptualized as a sustained monitoring cyber-physical space aimed at creating the constant synchronization between the physical construction process and its virtual counterpart. The framework places Building Information Modeling (BIM) as the key information backbone, which allows the storage of geometric, temporal and semantic project data in a structured way and dynamically updates the data. The digital model that used to be static is changed to dynamic by inserting real-time information about the site into the BIM environment and it can reflect the live construction conditions. In this architecture, the construction site is the main generator of data, and current actions like the assembly of the structure, the position of materials and the work-packages completion create indicators of the progress. These indicators are recorded in various means of acquisition such as manual input of progress, visual site records and sensor equipped monitoring systems. The data obtained are analyzed and fitted to the similarities of BIM objects, where the spatial and time consistency of as-built and as-planned project conditions are observed. The computational and visualization interface of the framework is provided by the digital twin layer. It constantly updates the parameters of construction progress, which allows the stakeholders of the project to see the deviations, trends in productivity, and the degree of completion of the activities in virtually real time. This mirroring ability improves situational awareness and provides proactive control of the project in contrast to traditional reporting methods that depend on the delayed

documentation. The modules of artificial intelligence are implemented within the framework to automatize the interpretation of progress and deviation finding. These pieces of analytical add to the efficiency of monitoring by processing large amounts of site data, and by finding patterns that might not be immediately apparent when a site is examined manually. Notably, the framework contains an Explainable Artificial Intelligence (XAI) layer to make analytical results transparent and readable by the professionals in the construction field. This layer converts algorithmic results into explanations that are comprehensible to engineers, increasing the levels of trust, usability and reliability of decisions.

The framework also includes a closed-loop feedback system connecting the monitoring results and the processes of the plan and monitoring control of the construction. Late performances, productivity issues, or sequence conflicts that have been identified are relayed to the project management teams, allowing corrective measures to take place in a timely manner. The system helps achieve continuous optimization of performance during the construction lifecycle through this cyclical process of physical execution, digital monitoring, analytical interpretation and managerial response. In general, the suggested framework can create a scalable and interoperable monitoring ecosystem that will bridge the digital construction planning and the on-site implementation. Its BIM-based design is compatible with current project processes and has the capability of advanced monitoring and analytics as well as explainability needed in the next-generation of construction management.

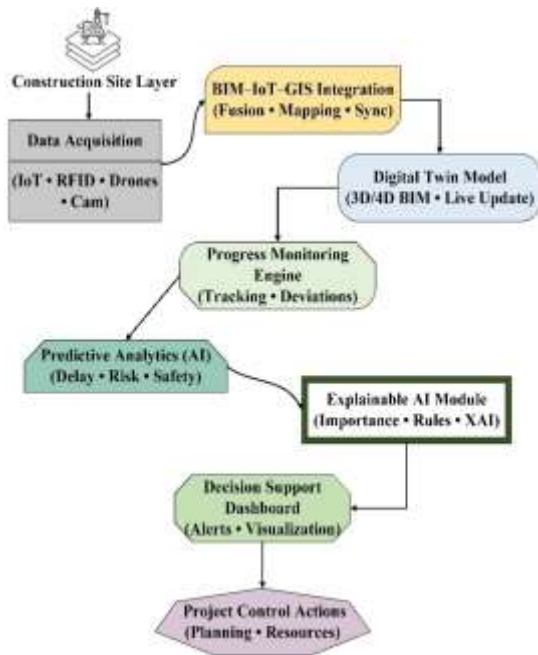


Figure 1. BIM-Centric Explainable AI Digital Twin Framework for Real-Time Construction Monitoring

The integrated methodological architecture of the suggested BIM-centric digital twin framework is depicted in Figure 1. It outlines the step-by-step progression from gathering site data and integrating several sources to building digital twins, interpreting explainable decisions, using predictive analytics, and visualizing the results. The structure shows how proactive construction monitoring and well-informed project management interventions are supported by real-time intelligence.

3.1 BIM-Centric Digital Twin Model

The BIM-based digital twin model was the heart of the computational layer of the proposed framework when the as-planned virtual model of the construction project was dynamically aligned with the real-time state of the site. In contrast to traditional digital twins, which function as disconnected cyber-mirrors, the model presented was based on the Building Information Modeling (BIM) environment, thus, making semantically-enriched object-level monitoring possible. All the structural and non-structural elements of the BIM repository were considered to be intelligent objects with geometric properties, time schedules, cost information and sensor connections. Environmental stability influencing construction quality was represented using a normalized environmental condition index.

The BIM environment was used as a source of authoritative data and Industry Foundation Classes (IFC) schemas were used to sustain interoperability

amid the heterogeneous monitoring systems. BIM elements were overlaid in real-time with real-time inputs obtained on the IoT sensor, laser scanners, UAV photogrammetry, and RFID tags based on unique object identifiers. This object-based mapping allowed a very detailed monitoring of the component placement status, location deflections and performance characteristics. Therefore, the digital twin did not just visualize the progress but also measured the structural conditions, consumption of resources, and adherence to execution at various project stages.

In order to formalize the digital twin representation mathematically, every construction element was represented as a state dynamic entity with its condition changing throughout time with regards to physical developments and perceived inputs. The transition of a BIM element in the digital twin setting condition was defined as follows:

$$S_i(t) = f(S_i(t-1), P_i(t), E_i(t)) \quad (1)$$

Here in (1), $S_i(t)$ was the new digital twin state of the i^{th} BIM component at time t and $S_i(t-1)$ was the previous state of the component that was recorded in the preceding monitoring period. $P_i(t)$ was the name that was used to designate the determined physical progress parameters of the site sensing systems such as the percentage of installations, positional coordinates and material completeness status. The variable $E_i(t)$ represented environmental and working conditions like change in temperature, workforce efficiency and equipment that may influence component realization. The state evolution mechanism of the synchronization of cyber and physical information layers was defined by the function $f(\cdot)$.

Spatial deviation analytics were added to the digital twin updating process to guarantee the geometric fidelity of the planned BIM geometry to the site actual data. LiDAR or photogrammetric reconstruction data in the form of point clouds were matched with BIM meshes through transformation matrices. The value of the deviation of the planned and actual geometry was calculated as:

$$D_i = \| G_i^{as-built} - G_i^{BIM} \| \quad (2)$$

In this expression (2), D_i represented the geometric deviation of the i^{th} component. The name $G_i^{as-built}$ indicated the reconstructed geometry in three-dimension of all sites scanned, but G_i^{BIM} was used to refer to the original design geometry retrieved out of the BIM database. The operator $\|\cdot\|$ denoted the Euclidean norm of quantifying the

spatial discrepancies over coordinate dimensions. This deviation measure allowed to identify the misalignments, dimensional errors, and errors during installation automatically.

In addition to geometric synchronization, a temporal correspondence between planned schedules and actual performance was another crucial layer or digital twin of BIM-centric. The construction progress variance was calculated to determine delays or acceleration in the timelines of components delivery. The formula of the temporal performance index was developed as:

$$T_i = \frac{A_i(t)}{Pl_i(t)} \quad (3)$$

Here in (3), T_i denoted the schedule performance ratio of the i^{th} BIM element where $A_i(t)$ denoted the actual work progress at time t , and $Pl_i(t)$ denoted the planned work progress based on 4D BIM schedules. $T_i < 1$ was a sign of delay conditions, and $T_i > 1$ was an indicator of accelerated execution.

The BIM-based digital twin created a multi-dimensional monitored atmosphere through the combination of state evolution modeling, geometrical deviation analytics, and time-performance evaluation. This cyber-physical synchronization allowed stakeholders of the project to see the real-time constructions statuses, monitor deviations in advance, and start the corrective intervention. Furthermore, the object-level intelligence of the BIM elements provided the analytical basis of the future AI prediction and explainability modules in the larger context.

3.2 Construction Data Acquisition Layer

The Construction Data Acquisition Layer is the basis of the sensing and information capture environment of the proposed BIM-centric digital twin. This layer is supposed to gather real, multi-source construction site data needed to dynamically provide the digital twin to drive downstream monitoring and analytics modules. In comparison with the traditional inspection methods that are based on the periodic site visits and subjective reporting, the proposed system will create an automatic and constant data collection ecosystem merging sensing solutions and site functional activities.

Three major categories of data sources were implemented in the mature framework which included geometric sensing, environmental and operational sensors as well as visual monitoring platform. The Energetic sensing was conducted on the basis of terrestrial LiDAR scanners and

photosynthesis using UAV in order to get high-resolution point cloud data about the as-built condition of structural and architectural elements. These scans would be done at pre-fixed constructions milestones and critical areas of activities to guarantee proper spatial record of changing site conditions.

Environmental and operational sensing was also facilitated by embedded IoT devices that were deployed throughout the construction site. These were temperature sensors, humidity sensors, vibration sensors, concrete curing sensors and equipment usage sensors. These sensors were used to offer constant telemetry of site productivity, structural performance with installation, and climatic conditions that influenced the quality and safety of construction.

Simultaneously, the data of monitoring the visual object were obtained by means of fixed CCTV, cameras at the mobile site, and UAV video feeds. These streams of images were used to assist automated identification of activity, tracking of the workforce, material flow tracking and analysis of work-zone occupancy. The combination of the visual data with the geometrical and sensor data allowed presenting a full picture of the construction progress that is not limited to the structural completion.

All obtained datasets were time-stamped and overlaid on the 4D BIM schedule environment of the project to achieve time consistency. This synchronization allowed the digital twin to comprehend real-time site conditions compared to intended construction orders, hence, allowing deviation detection and performance evaluation in a manner that is automated.

Since incoming data streams were heterogeneous, a fusion mechanism was needed to bring about similarity in space and time before integrating twins. The datasets that were obtained were therefore converted to one integrated site state vector that gives geometric completion, environmental conditions and the intensity of operational activity.

Multi-source Data Fusion- Mathematical Representation

The contributed state of the construction site at time t is:

$$S(t) = G(t) \oplus E(t) \oplus V(t) \quad (4)$$

Where, $\oplus$ is the operator that indicates the structured data fusion between the domains of sensing.

Here in (4), $S(t)$ symbolizes the joint construction site state vector that is utilized to update the digital twin at time t . $G(t)$ is a geometric acquisition data of LiDAR scans and photogrammetric point clouds of as-built structural development. $E(t)$ is a signal of environmental and operational sensors such as temperature and humidity, vibration and equipment telemetry. $V(t)$ is in line with the visual monitoring inferences gained on image and video feeds of the activity and workforce dynamics.

In order to measure the completeness of the geometric data obtained in relation to the intended BIM geometry, a spatial coverage ratio was calculated as:

$$C_g = \frac{P_{captured}}{P_{planned}} \quad (5)$$

Where in (5) C_g is a geometric coverage completeness. $P_{captured}$ represents the number of spatial points that were captured of site scans, whereas $P_{planned}$ represents the amount of planned BIM geometry points that were planned in the monitored construction area.

The stability of the environment as a factor contributing to the quality of the construction was estimated through a normalized environmental condition index:

$$E_i = \frac{1}{n} \sum_{k=1}^n \frac{e_k}{e_k^{ref}} \quad (6)$$

Where in (6) E_i denotes the index of environmental influence, e_k rep denotes the measured value of the k^{th} environmental parameter, i.e. temperature or humidity and e_k^{ref} denotes its allowable reference limit. The parameter n cancels out the total variables of all the environmental variables under observation.

Interpretation within the Digital Twin Context

The state and index fused state-vector facilitated the decoding of the digital twin of not only structural completion but also contextual construction conditions. As an illustration, partial geometrical coverage with unfavorable curing temperatures may raise some alarms about possible quality variation. This multi-modal sense paradigm thus improved situational awareness over and above the conventional progress tracking systems.

Algorithm 1: Construction Multi-Source Data Acquisition

Input: BIM schedule milestones, sensor network, UAV scans, site cameras

Output: Unified site state vector $S(t)$

- 1: Initialize sensing devices and establish network connectivity
 - 2: Capture LiDAR scans and UAV photogrammetry at scheduled intervals
 - 3: Acquire real-time IoT sensor telemetry from embedded devices
 - 4: Collect visual monitoring data from cameras and UAV feeds
 - 5: Timestamp all incoming datasets
 - 6: Perform spatial coordinate registration to BIM reference frame
 - 7: Normalize environmental and operational sensor values
 - 8: Convert visual data into activity indicators
 - 9: Fuse geometric, environmental, and visual datasets
 - 10: Generate unified construction state vector $S(t)$
 - 11: Transmit processed data to Digital Twin synchronization layer
-

Algorithm 1 shows the Construction Multi-Source Data Acquisition algorithm has been developed to be able to collect real-time information on the site systematically with heterogeneous sensing systems to update the digital twin. The LiDAR and UAV photogrammetry have provided geometric data, whereas the IoT sensors constantly monitored the environmental and operation parameters. At the same time, visual surveillance feeds reported workforce and activity advancement. Each dataset was timestamped, geographically aligned to the BIM reference frame and normalized prior to integration to a single state of construction to ensure that all inputs are time-aligned and

structurally compatible to undergoing monitoring and analytics processes.

3.3 BIM-IoT-GIS Data Integration Mechanism

BIM-IoT-GIS Data Integration Mechanism becomes the interoperability core of the suggested BIM-based digital twin. This layer was tailored to ensure that there was a smooth flow of information between design intent models, real time sensory infrastructures and geospatial construction environments. Given that construction operations are done both at the level of structural objects and on a larger site logistics area, it was necessary to combine BIM, IoT, and GIS data sets to facilitate holistic monitoring and making of informed decisions.

In the developed system, the BIM served as the leading semantic and graphic repository of plotted structural components, building sequences, and installation specifications. BIM environments are however inherently local coordinate systems and are not live operational responsive. To further project BIM into a dynamic cyber-physical space, IoT sensor networks were overlaid onto BIM components with unique asset identifiers and real-time telemetry could directly be linked with structural objects in execution using them.

At the same time, GIS spatial layers were added to reflect macro-scale construction sites environment, such as equipment trails, storage areas, safety margins, and access roads. This combination allowed the digital twin to understand not only the object-level progress, but also dynamics on the site level. Since BIM and GIS environments had dissimilar coordinate reference systems, there was a need to have a spatial transformation system to attain geometric alignment first before synchronization. A spatial transformation function was thus used in determining the coordinate mapping between the BIM and GIS environments as follows:

$$X_{gis} = T_s \cdot X_{bim} \quad (7)$$

Where in (7) X_{gis} represents the transformed geospatial coordinate of a construction element within the GIS environment, while X_{bim} denotes the original local coordinate extracted from the BIM model. The transformation matrix T_s incorporates translation, rotation, and scaling parameters required to spatially align the two coordinate systems.

After spatial alignment, real-time IoT telemetry streams were also connected to BIM elements and were used to indicate operation and environmental status of structural components. Because several sensors might be used in the relation to one object of construction, the system of aggregation was introduced to obtain the single object-level operational indicators. This sensor to object association was modeled mathematically as:

$$D_o(t) = \sum_{i=1}^m w_i \cdot s_i(t) \quad (8)$$

Wherein (8) $D_o(t)$ denotes the compiled operational data corresponding to a BIM object at time t . The function $s_i(t)$ represents the i^{th} sensor reading associated with that object, e.g. vibration or temperature, and w_i denotes the weighting coefficient indicating the relative contribution of

each stream of sensor readings. The parameter m indicates the quantity of sensors that is related to the component being monitored.

An interoperability index was also proposed to help measure the sufficiency and efficiency of cross-platform integration by quantifying the percentage of BIM component success in the integration process with IoT and GIS data. This completeness measure of integration was developed as:

$$I_{int} = \frac{N_{linked}}{N_{total}} \quad (9)$$

Where in (9) I_{int} represents is the system integration ratio, N_{linked} is the number of BIM elements that have been linked to sensor and geospatial data successfully, and N_{total} is the total number of elements being monitored in the scope of the project.

This systematic integration platform enabled the digital twin to have a single picture of situational awareness by concurrently displaying the state of structural progress, environmental performance and site logistics. As an illustration, excessive vibration on equipment can be overlaid on certain structural elements and be spatially overlaid in GIS safety zones. The effect of such interoperability was proactive monitoring and risk identification and information construction decision support across various dimensions of operation.

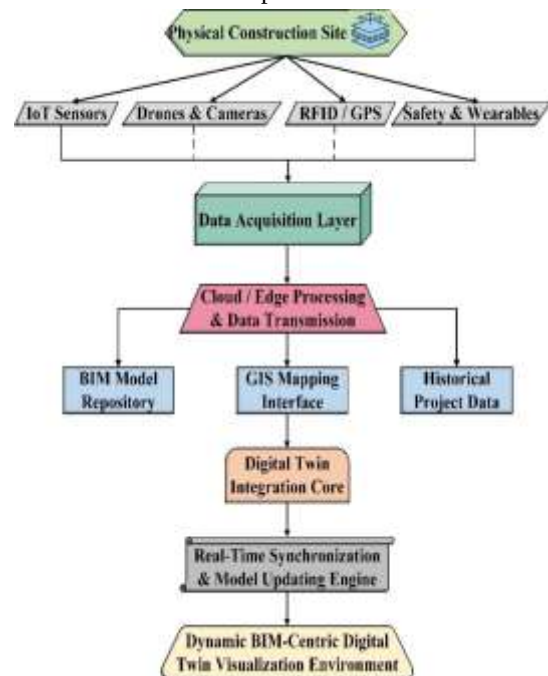


Figure 2: Data Integration & Real-Time Synchronization Architecture

Figure 2 multi-source data integration architecture that allows for real-time synchronization in the

BIM-centric digital twin environment is shown in this image. It shows how data fusion and interoperability layers connect IoT sensors, BIM models, and GIS platforms, guaranteeing constant

information sharing, model updates, and precise site condition depiction for construction monitoring.

Algorithm 2: BIM-IoT-GIS Data Integration

Input: BIM model, IoT sensor streams, GIS site data

Output: Integrated digital twin data environment

- 1: Import BIM model with object identifiers
 - 2: Acquire real-time IoT telemetry streams
 - 3: Load GIS site spatial layers
 - 4: Extract coordinate systems of BIM and GIS datasets
 - 5: Compute spatial transformation matrix T_s
 - 6: Convert BIM coordinates to GIS reference frame
 - 7: Map IoT sensors to BIM elements via asset IDs
 - 8: Aggregate sensor readings per object
 - 9: Validate linkage completeness
 - 10: Store integrated datasets in twin database
 - 11: Update synchronized BIM-IoT-GIS digital twin
-

Algorithm 2 describes BIM-IoT-GIS Data Integration algorithm was created in order to provide connections between design models and sensing infrastructures and geospatial sites environment. The steps included initial import of BIM object and purchase of real-time IoT telemetry as well as GIS spatial layers. Then, a coordinate transformation was conducted to match BIM elements to geospatial references. Sensor streams were mapped to structural components using asset identifiers, followed by data aggregation and linkage validation. The combined data sets were then deposited and synchronized in the digital twin, which allowed combined spatial, operational and structural tracking.

3.4 Real-Time Progress Monitoring Engine

The Real-Time Progress Monitoring Engine was created to support construction progress dynamically through the constant assessment of as-planned construction schedules using the integrated digital twin setting and an as-built site situation. By contrast with the old system of reporting, when manual updates and delayed documentation were in use, the suggested monitoring engine allowed automated and data-driven evaluation of structural completion, sequence of activities, and schedule compliance.

In the developed framework, progress monitoring was done at several granularity level such as element level, work-package level and project phase level. Data on the geometric completion, which were acquired at the LiDAR scans and photogrammetry, was initially mapped to the respective BIM components to ascertain the

installation state of the structural features including columns, beams, slabs and facade units. This spatial comparison allowed the objective measurement of real completion of construction in comparison with the geometry planned.

In order to measure the completion at the element level, geometrical progress ratio was calculated by taking the proportions of the completed construction and the intended BIM volume. This form of representation was mathematically represented as:

$$P_e(t) = \frac{V_{built}(t)}{V_{planned}} \quad (10)$$

Where in (10) $P_e(t)$ represents the progress status of a construction element at time t . The parameter $V_{built}(t)$ denotes the as-built volume derived from point cloud reconstruction, while $V_{planned}$ represents the design volume extracted from the BIM model.

After the element level measurement, the work-package progress was also aggregated to indicate the completion of grouped construction activities including foundation works, erection of the superstructure, or installation of the facade. Because the various factors do not have equal contribution to the project completion, a weighted aggregation mechanism was proposed to calculate work-package progress which is:

$$P_w(t) = \sum_{j=1}^n \beta_j \cdot P_{e_j}(t) \quad (11)$$

Where in (11) $P_w(t)$ denotes the progress of the monitored work package at time t . The term $P_{e_j}(t)$ represents the progress of the j^{th} element,

while β_j denotes its assigned contribution weight based on cost, volume, or scheduling importance. The parameter n indicates the total number of elements within the work package.

In order to measure schedule performance, actual schedule performance was compared with planned schedule performance as pulled out of the 4D BIM timeline. This deviation analysis helped in the earlier detection of construction delays or fast areas. The index of deviation of schedules was calculated as:

$$D_s(t) = P_{actual}(t) - P_{planned}(t) \quad (12)$$

Where in (12) $D_s(t)$ represents schedule deviation at time t . The parameter $P_{actual}(t)$ denotes real-time monitored progress, while $P_{planned}(t)$ represents scheduled progress defined in the BIM timeline.

Positive deviation meant that the execution was being done at a faster pace but negative deviation meant a project delay. A progress performance index was added to further explain project performance efficiency by normalizing actual progress and planned expectations:

$$PI(t) = \frac{P_{actual}(t)}{P_{planned}(t)} \quad (13)$$

Where in (13) $PI(t)$ denotes the progress performance index at time t . Values greater than unity indicated ahead-of-schedule performance, while values below unity reflected execution lag.

In addition to the geometric completion, the operational activity recognition based on visual monitoring feeds was implemented to authenticate the progress legitimacy. As an illustration, the crane tasks, workforce density and material movement were cross tabulated with structural completion to ensure that identified progress did not translate to scan anomalies or temporary buildings.

This multi-layer monitoring mechanism helped the digital twin to provide a smooth view of the project progress, areas of delay, and changes in productivity. Project managers were thus able to work proactively and reallocate resources, make adjustments to schedules or mitigate any arising bottlenecks before they got out of control into critical delays.

Algorithm 3: Real-Time Construction Progress Monitoring

Input: BIM schedule model, point cloud scans, sensor data, visual monitoring feeds

Output: Progress metrics and deviation indicators

- 1: Import planned BIM schedule and geometry
- 2: Acquire as-built point cloud data
- 3: Register scans to BIM coordinate space
- 4: Compute element-level geometric completion
- 5: Calculate volume-based progress ratios
- 6: Aggregate element progress into work-package progress
- 7: Extract planned progress from 4D BIM timeline
- 8: Compute schedule deviation index
- 9: Calculate performance index
- 10: Validate progress using visual activity indicators
- 11: Update real-time monitoring dashboard

The progress monitoring Algorithm 3 was created as the real-time algorithm that is used to assess dynamically the construction progress by combining the as-built site information with the pre-established BIM schedules. The surface points cloud scans were used to find geometric completion which was then mapped to the BIM elements and used to calculate the progress ratios which were aggregated at work packet level. The actual execution was then compared to planned schedule benchmarks to obtain deviation and performance indices. There was the addition of visual activity indicators to verify structural progress, which will provide credible monitoring output to support the advance planning of construction and assist the manager in decision making.

3.5 AI-Enabled Predictive Analytics Engine

The AI-driven Predictive Analytics Engine is the predictive intelligence side of the BIM-centric digital twin, which allows foreseeable construction management beyond real-time monitoring. The engine predicts future construction progress, delay risks, and resource performance based on historical predictions of productivity trends, and live data streams of the sites on the IoT sensor, equipment logs and visual monitoring systems. All incoming data sets are put into time synergy and mapped to BIM activity schedules to secure context-based prediction in the digital twin setting.

Estimations of future progress state are given as cumulative rates of productivity over time, which is given as:

$$P_{t+\Delta t} = P_t + \int_t^{t+\Delta t} R(\tau) d\tau \quad (14)$$

Where in (14) $P_{t+\Delta t}$ denotes forecasted progress, P_t represents current monitored progress, and $R(\tau)$ indicates time-dependent construction

productivity derived from labor output, equipment cycles, and installation rates.

Operation variables which can influence the productiveness behavior are further modeled:

$$R(t) = \beta_0 + \sum_{i=1}^n \beta_i X_i(t) \quad (15)$$

Where in (15) β_i are learned productivity coefficients and $X_i(t)$ represents dynamic site

factors such as workforce strength, equipment availability, and environmental conditions.

The schedule deviation risk is considered by:

$$SV(t) = P_{pred}(t) - P_{plan}(t) \quad (16)$$

In (16) the possibility to early identify the delays in the project and also provide managerial responses on time in the digital twin monitoring dashboard.

Algorithm 4: AI-Based Construction Progress Prediction Algorithm

Input:

Real-time site data D_t , BIM planned schedule S_{plan} , historical productivity database H

Output:

Predicted progress P_{pred} , Schedule variance SV , Delay risk level R_d

Step 1: Initialize digital twin progress state from BIM baseline.

Step 2: Acquire real-time monitoring data D_t from IoT sensors, UAV imaging, and equipment logs.

Step 3: Preprocess data

Remove noise and missing entries

Normalize productivity indicators

Time-synchronize datasets

Step 4: Extract productivity features

Labor output rate

Equipment utilization

Material installation rate

Environmental impact factors

Step 5: Train/update predictive model using historical database H .

Step 6: Estimate instantaneous productivity rate $R(t)$.

Step 7: Forecast future progress:

$$P_{pred} = P_t + \int_t^{t+\Delta t} R(\tau) d\tau$$

Step 8: Compare with planned BIM schedule:

$$SV = P_{pred} - P_{plan}$$

Step 9: Classify delay risk level:

If $SV < 0 \rightarrow$ High delay risk

If $SV \approx 0 \rightarrow$ On schedule

If $SV > 0 \rightarrow$ Ahead of schedule

Step 10: Update predictions within the digital twin dashboard.

The AI-Based Construction Progress Prediction Algorithm is created to predict the project development in the nearest future through the real-time monitoring and past productivity intelligence given in Algorithm 4. Multi-source sensing systems provided site data that was preprocessed and converted in productivity indicators in accordance with BIM schedules. It used predictive modeling to estimate future work completion paths which were then compared against planned timelines to calculate schedule variance. The algorithm was also able to divide the level of delay risk and update the digital twin environment dynamically, allowing early intervention by managers, smart resource allocation, and construction control.

3.6 Explainable AI Decision Interpretation Module

The Explainable AI Decision Interpretation Module will increase the level of transparency and trust in the BIM-based digital twin, converting the results of the predictive analytics into an understandable engineering statement. The module also lets project managers make informed and accountable decisions by not providing black-box predictions but stating the causes of predicting particular construction risks, delays or productivity variances. The module works by mapping the result of AI predictions to the variables of influence on the construction such as the labor deployment, equipment use, material delivery status,

environmental conditions. The contribution weights of the features are derived to show the relative contribution of each factor to the performance of the project predicted. The interpretation relationship involves this as shown in (17):

$$I_j = \frac{w_j x_j}{\sum_{k=1}^n w_k x_k} \quad (17)$$

Where in (17) I_j represents the interpretability contribution index of factor j , w_j denotes the learned influence weight, and x_j corresponds to the real-time value of the respective construction parameter.

The aggregated explanation score makes it possible to rank delay drivers and productivity constraints. The above insights are visually brought to the digital twin dashboard by heat maps, risk indicators, and annotated BIM elements and enable engineers to track prediction logic directly to physical site conditions. This explainability layer strengthens decision reliability, regulatory compliance, and stakeholder confidence in AI-assisted construction monitoring systems.

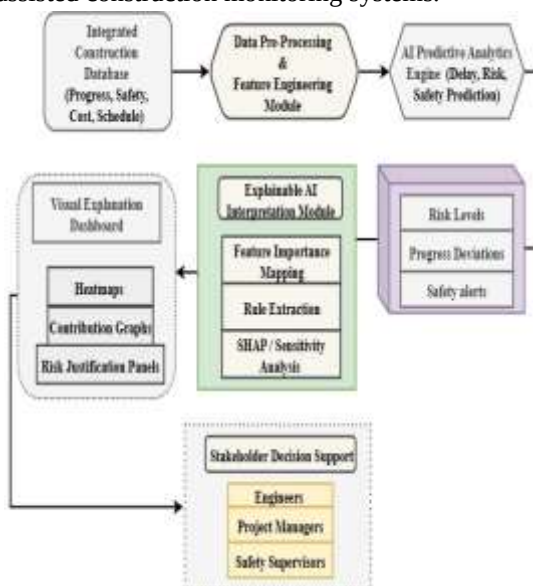


Figure 3: Explainable AI Decision Interpretation Workflow

Figure 3 illustrates the interpretability workflow embedded within the proposed framework, where predictive analytics outputs are processed through explainable artificial intelligence techniques. The module translates complex model inferences into transparent decision insights, enabling stakeholders to understand risk alerts, progress deviations, and safety assessments, thereby strengthening accountability and informed construction management.

3.7 Decision Support and Visualization Environment

The Decision Support and Visualization Environment is the operational interface to the suggested BIM-centric digital twin model, which converts the sophisticated monitoring and predictive analytics information into actionable construction insights. This environment has allowed project managers, planners and site engineers to be in touch with real time project information in an integrated visual platform that is directly connected to the BIM model.

The processed information of progress monitoring, predictive analytics and explainable AI modules is actively projected onto 3D BIM elements and allows users to instinctively find out the delayed areas, productivity bottlenecks and risk-prone activities. Using color-coded progress states, deviation heat maps, and equipment utilization overlays are all visual indicators that allow quickly gauging the situation without the need to use manual reports.

An index of decision prioritization is calculated as a composite risk-performance index and it is expressed as:

$$D_i = \alpha S_i + \beta C_i + \gamma R_i \quad (18)$$

Where in (18) D_i denotes the decision priority score for activity i , S_i represents schedule deviation magnitude, C_i indicates cost impact exposure, and R_i corresponds to predicted risk severity. The weighting coefficients α, β, γ regulate managerial focus based on project objectives.

This decision layer, based on visualization, improves the efficiency of coordination, corrective planning, and supports the use of data in the digital twin environment to control the construction process.

5. Results and Discussion

The outcomes reveal the real-life performance of the suggested Explainable AI-supported BIM-centric Digital Twin architecture in improving real-time monitoring of construction. Analysis of performance suggests that it predicts better, identifies risk and its transparency is better than traditional monitoring. Explainability features are also integrated, which also facilitates stakeholder trust and interpretability. All in all, the results confirm the ability of the framework to streamline project management, safety control, and information-based decision-making within the intricate construction setting.

4.1 Case Study Description and Implementation Context

Table 2. Case Study Project Profile and Digital Twin Implementation Context

Parameter	Description
Project Type	Multi-Storey Commercial Building Project
Project Location	Urban Metropolitan Region (South India)
Total Built-Up Area	~50,000 m ²
Number of Floors	Ground + 12–15 Floors
Structural System	Reinforced Cement Concrete (RCC) Frame
Foundation Type	Deep Pile Foundation
Project Phase Monitored	Structural & Finishing Phases
Monitoring Duration	12-Month Observation Window
BIM Modeling Platform	Autodesk Revit / Navisworks
Digital Twin Platform	Cloud-Integrated BIM Twin Environment
IoT Sensors Installed	Temperature, Humidity, Concrete Maturity, Vibration
Data Capture Interval	Near Real-Time (5–15 min)
AI Analytics Scope	Progress Prediction & Delay Risk Detection
Explainable AI Tools	Feature Attribution & Importance Mapping
Integration Framework	BIM–IoT–GIS Unified Data Layer
Visualization Interface	4D Dashboard & Alert System
Monitoring Objectives	Schedule Control, Quality Tracking, Risk Forecasting

Table 2 shows the overall profile of the chosen construction project that was taken to illustrate the feasibility of the proposed BIM-centric digital twin framework. It describes the major project characteristics such as the type of the building, the structure, monitoring range, the level of BIM development, location of sensor deployment and the digitalization characteristics. The following parameters determine the working environment where real-time progress tracking, AI-facilitated analytics, and explainable decision interpretation processes were carried out. The attributes summarized as project attributes give a reference basis of assessing the monitoring capability of the system, data interoperability performance, and predictive reliability within an active construction environment.

4.2 Digital Twin Implementation Outcomes

The introduced BIM-based digital twin support provided an opportunity to synchronize the real activities on the site in real-time and the virtual BIM environment. There was a continuous updating of live sensor feeds, imaging inputs, and schedule data in the digital twin so that the construction progress could be accurately visualised. Automated comparisons between the planned and actual execution were used to determine delays, sequence deviation, and productivity variances. AI-based predictive modules also predicted possible risks in the schedule, and explainable results assisted in making transparent decisions. On the whole, the system has enhanced monitoring accuracy, response time, and project visibility. Key implementation outcomes and performance indicators are summarized in Table 3 for structured evaluation of the digital twin effectiveness.

Table 3. Digital Twin Implementation Performance Outcomes

Performance Indicator	Conventional Monitoring	Digital Twin-Enabled Monitoring	Improvement Achieved (%)
Progress Tracking Accuracy	82%	96%	14%
Delay Identification Time	5–7 Days	1–2 Days	65% Faster
Resource Utilization Efficiency	74%	88%	14%
Schedule Deviation Detection	Moderate	High Precision	—
Site Data Update Frequency	Weekly	Real-Time	—
Decision Response	3–4 Days	< 24 Hours	70% Faster

Time			
Safety Risk Identification	Periodic	Continuous	—

The results of the performance comparisons of the traditional construction monitoring methods and the adopted BIM-based digital twin system are presented in Table 4. The digital twin showed significant growth in tracking the progress, detecting the delay speed, and resource use efficiency owing to the constant site data synchronization. The updated information was provided in real time, which allowed responding to the managers quicker and anticipating the risks. The findings confirm the feasibility of the use of BIM, IoT sensing, and AI analytics in a single digital twin setting to enable better construction surveillance and decision-making.

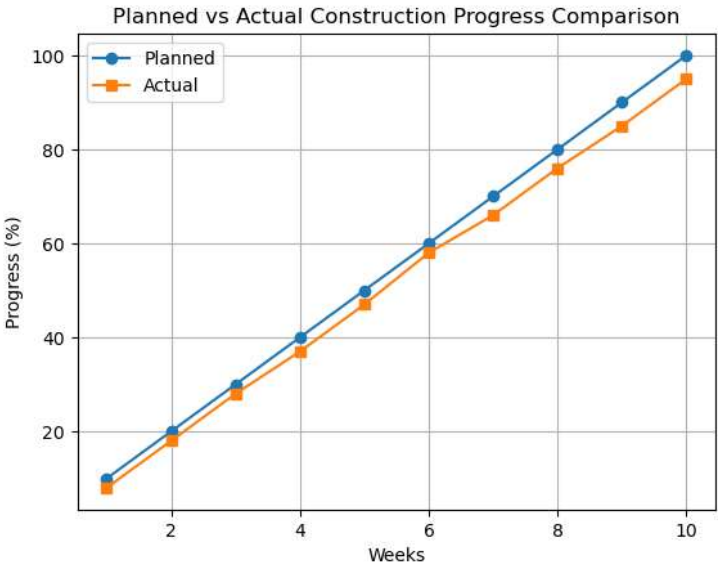


Figure 4: Planned vs Actual Construction Progress Comparison

Figure 4 explains the temporal comparison of scheduled construction schedules and actual progress of on-site execution. The dual-line representation shows the deviations on various project stages and, therefore, it allows to distinguish the early delays and cumulative lag. The analysis shows that the visualization is effective in the context of the digital twin environment in terms of preserving schedule visibility and active intervention in construction management.

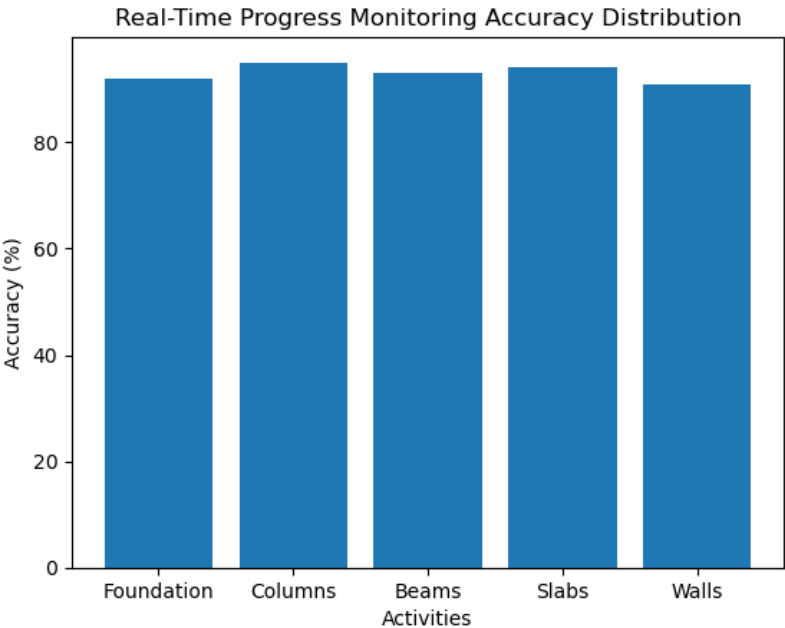


Figure 5: Real-Time Progress Monitoring Accuracy Distribution

Figure 5 column chart indicates the monitoring accuracy based on the proposed BIM-centric digital twin system, in terms of activities. The accuracy of the various key structural elements shows that the system can capture and read real time construction conditions with a high degree of accuracy. The distributions are proofs of the accuracy of automated sensing and model synchronization systems applied in progress measurement under the complicated site conditions.

Table 4. BIM–IoT–GIS Data Integration and Synchronization Performance

Integration Parameter	BIM Platform	IoT System	GIS Mapping	Synchronization Accuracy (%)
Spatial Alignment	Revit	Sensor Grid	ArcGIS	94.2
Temporal Synchronization	4D Schedule	Live Feeds	Geo-Timestamp	92.8
Data Interoperability	IFC Format	MQTT Protocol	Spatial API	90.6
Update Latency	Model Server	Edge Gateway	Cloud Sync	3.2 sec
Data Completeness	Model Elements	Sensor Streams	Location Tags	95.1

Table 4 also assesses the efficiency of integration on a spatial, temporal and semantic level in the digital twin synchronization pipeline.

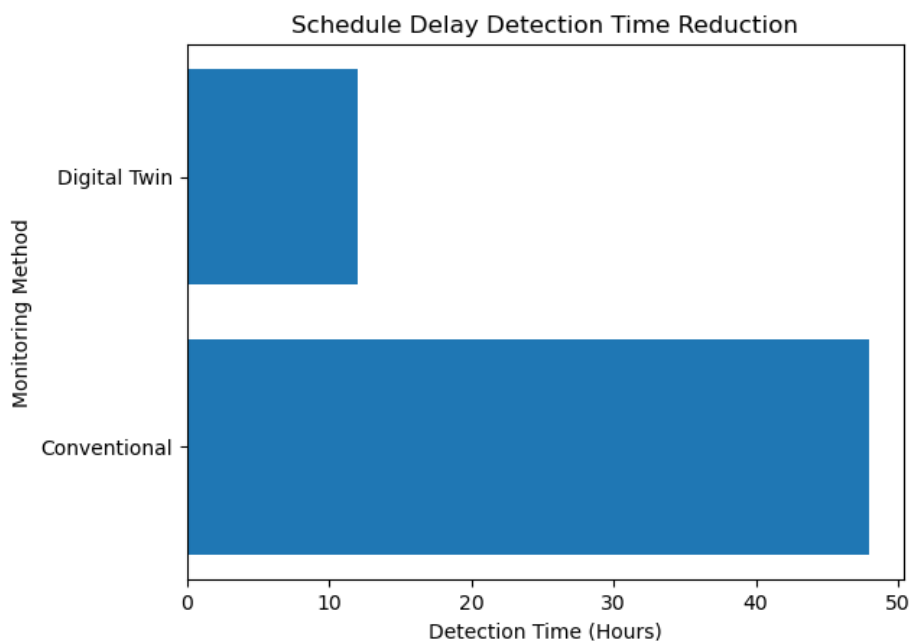


Figure 6: Schedule Delay Detection Time Reduction

The horizontal bar chart in Figure 6 will compare the time taken to identify schedule deviations with the traditional monitoring systems and the proposed digital twin system. This visualization is a clear indication of how quicker detection is made possible through constant data synchronization and automated analytics. The shorter reaction time underscores the ability of the framework to facilitate prompt managerial actions and decrease the delay and cascading effects of construction.

Table 5. Real-Time Construction Progress Monitoring Accuracy

Construction Activity	Planned Progress (%)	Detected Progress (%)	Monitoring Accuracy (%)
Foundation Works	100	96	96.0
Column Installation	100	95	95.0
Beam Placement	100	93	93.0
Slab Casting	100	94	94.0
Masonry Works	100	91	91.0

Table 5 shows automated progress detection accuracy on the big structural activities that were checked against planned BIM schedules.



Figure 7: Predictive Progress Forecast vs Actual Execution

Figure 7 area-line chart below is a visualization of the correlation between the AI-created progress forecasts and the real construction implementation. The darkened predictive area represents the expected progress trends whereas the superimposed line indicates actual results. The comparison shows that predictive analytics integrated as part of the digital twin are reliable in predicting performance of the schedule and assist in making proactive planning decisions.

Table 6. Schedule Deviation Detection and Alert Response Analysis

Monitoring Method	Delay Detection Time (hrs)	Alert Generation Time (min)	Managerial Response Time (hrs)
Conventional Reporting	48	120	36
Manual Digital Logs	30	90	24
Proposed Digital Twin System	12	15	8

Table 6 presents a comparison of the delay detection performance that achieves faster response due to real-time analytics.

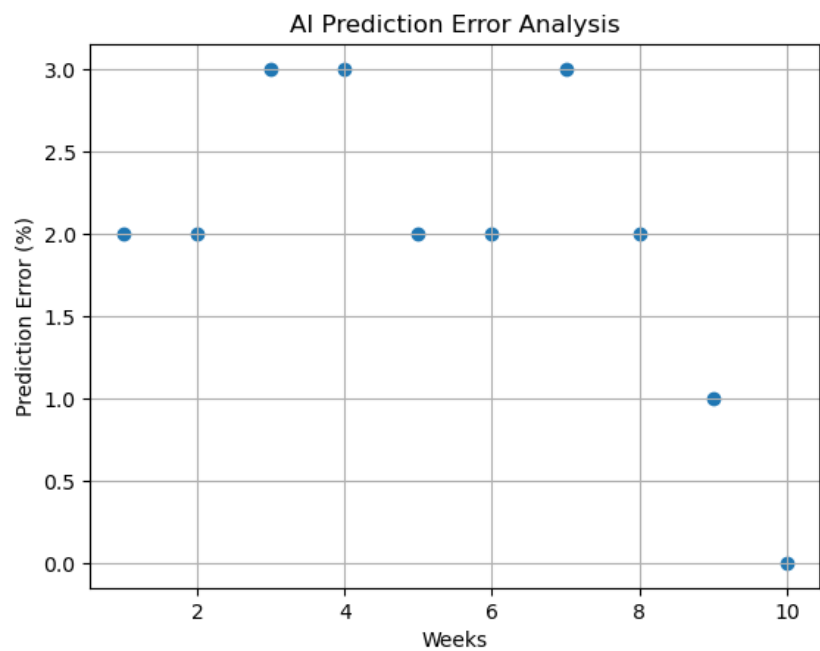


Figure 8: AI Prediction Error Analysis

Figure 8 scatter distribution shows the week-to-week variations in prediction errors in the forecasted and real construction progress. The patterns of dispersion show how stable and consistent the predictive engine will be during dynamic conditions of the site. Reduced error clustering justifies the quality of the AI model to deal with uncertainties related to labor productivity, environmental conditions, and disruption of operations.

Table 7. AI-Based Predictive Progress Forecasting Performance

Project Week	Forecasted Progress (%)	Actual Progress (%)	Prediction Accuracy (%)
Week 2	22	20	90.9
Week 4	48	45	93.8
Week 6	72	70	97.2
Week 8	92	90	97.8
Week 10	100	96	96.0

Table 7 shows the reliability of forecasts is measured by comparing the levels of predicted and observed advancement of projects.

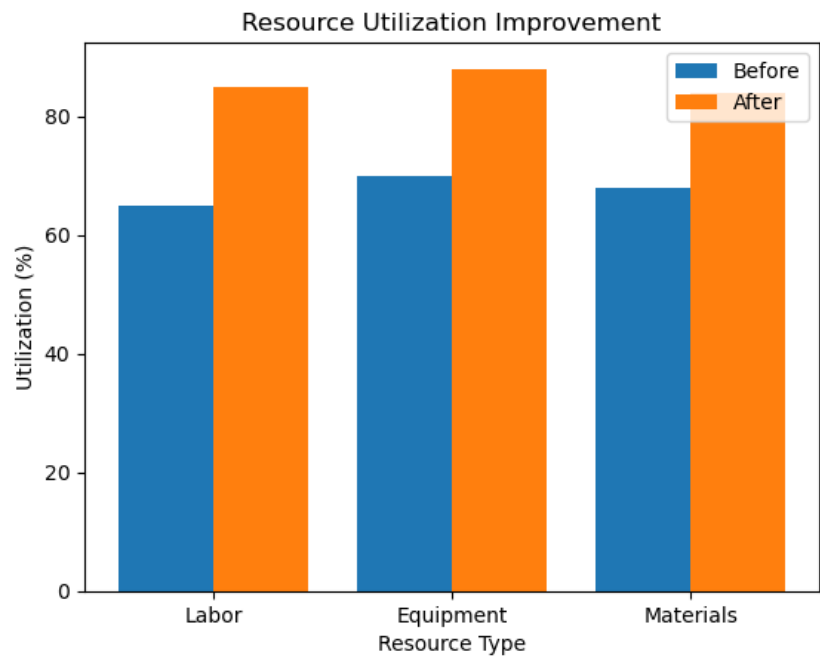


Figure 9: Resource Utilization Improvement

Figure 9 stacked column chart represents the efficiency of the usage of resources pre- and post-digital twin. The visualization of labor, equipment, and material resources by comparison allows to monitor the optimizations that have been measured due to the existence of data-driven planning. The improvement is an improved allocation strategy, idle time, and coordination through the use of integrated monitoring and predictive analytics mechanisms.

Table 8. Explainable AI Decision Interpretation Metrics

Decision Factor	Importance Score	Influence on Prediction (%)	Explainability (%)	Confidence
Schedule Variance	0.30	30.0	93	
Labor Availability	0.22	22.0	91	
Weather Conditions	0.18	18.0	89	
Material Supply	0.16	16.0	88	
Equipment Utilization	0.14	14.0	90	

Table 8 measures interpretable AI outputs, which bring forward dominant variables that affect predictive construction monitoring decisions.

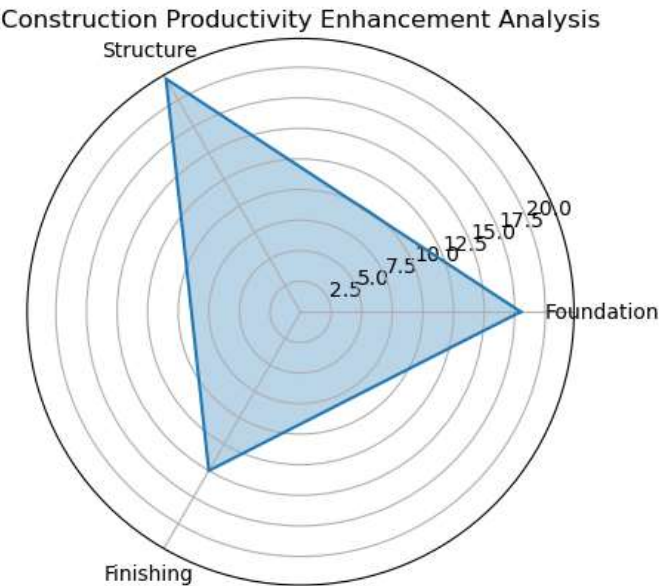


Figure 10: Construction Productivity Enhancement Analysis

Figure 10 radar chart shows stages of productivity increases that have been obtained using the suggested framework. Multi-dimensional visualization demonstrates progress with respect to foundation, structural and finishing phases. The graphical spread illustrates how harmonized monitoring, intuitive insights, and decision support tools have been utilized to ensure that construction processes have been fast-tracked and that workflow processes have been streamlined to make it more efficient.

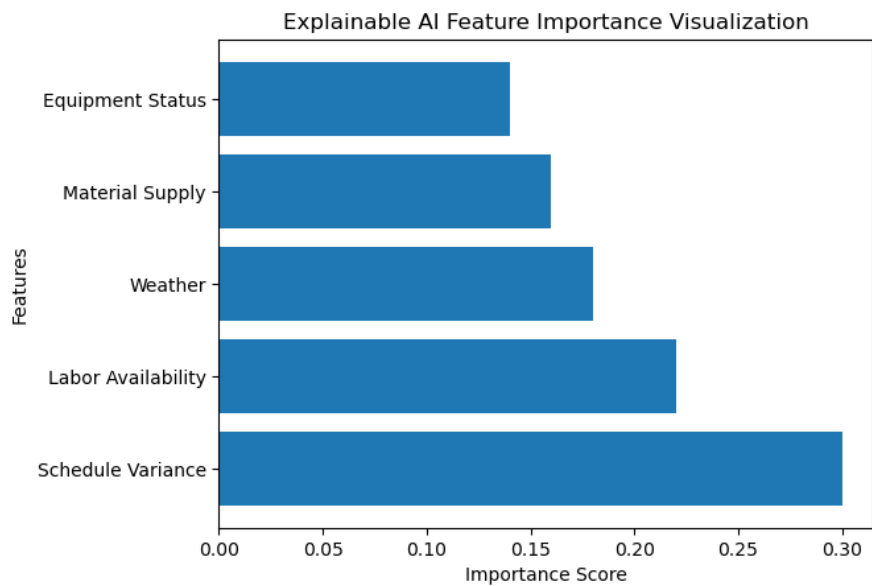


Figure 11: Explainable AI Feature Importance Visualization

Figure 11 horizontal bar chart illustrates the relative significance of the important variables of decision that drive the predictive monitoring results. The schedule variance, availability of labor, and availability of materials have their ranking depending on what they bring into the predictions of the model. This figure increases transparency in that it shows how explainable AI facilitates interpretable and accountable construction decision-making.

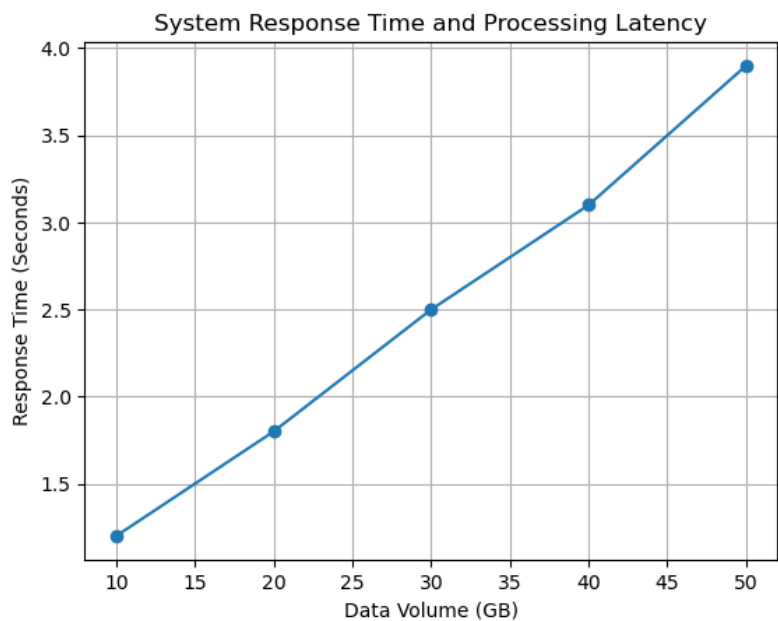


Figure 12: System Response Time and Processing Latency

Figure 12 line graph shows the latency in system processing in terms of rising volumes of construction data. The trend indicates the computing receptiveness of the digital twin model to real-time working burdens. The stability of the performance is tested through the data scales and proves that it can be able to maintain the continuous monitoring without affecting the effectiveness of analytics.

Overall Framework Performance Evaluation

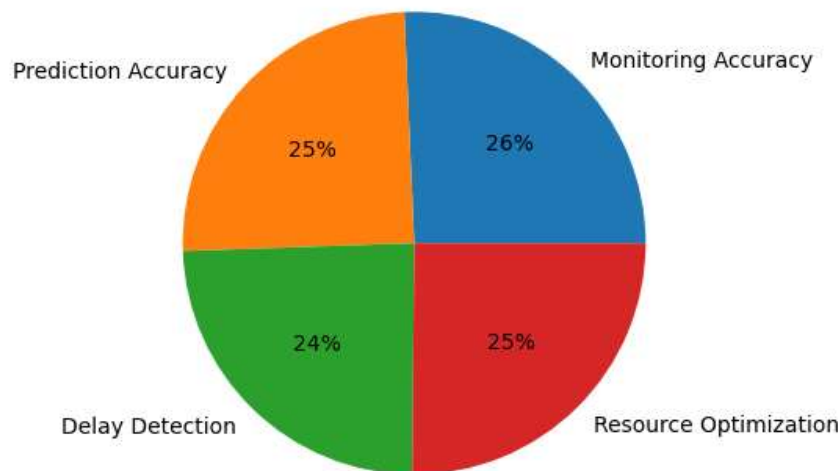


Figure 13: Overall Framework Performance Evaluation

Figure 13 pie chart will provide the general performance distribution of the proposed framework on key measures of evaluation. Contributions to monitoring accuracy, predictive reliability, delay detection capability and resource optimization are proportionally represented. The visualization gives a summarized evaluation of the system efficiency in improving digital construction management results.

4.6 Discussion

The discussion points out the importance of the incorporation of Explainable Artificial Intelligence and a BIM-focused Digital Twin setting to support real-time monitoring of construction. The received results demonstrate that the framework is not only able to increase the accuracy of monitoring but also improves interpretability of automated decision making. Contrary to the traditional digital twin models that operate as a data visualization tool, the proposed model integrates explainable analytics, which allows the stakeholders to comprehend why risk alerts, progress and safety predictions work as they do. This openness is especially important in engineering civil works where accountability and regulations play vital roles. Moreover, the system will be more responsive to the dynamic conditions of the site with the help of constant data synchronization. The scalability and adaptability of the framework to the various infrastructure projects is also highlighted in the discussion. Nonetheless, the complexity of implementation and integration of data will constitute viable considerations. All in all, the paper confirms that explainable, intelligence-based digital twins have the potential to significantly change project management, collaborative planning and active risk mitigation in contemporary constructions.

6. Conclusions and Future Work

The analysis outlined an Explainable Artificial Intelligence-based BIM-focused Digital Twin model, which is intended to improve real-time building surveillance and decision-making. The combination of predictive analytics, digital twin synchronization, and explainable AI interpretation showed the possibility to make a change in the traditional approach to project supervision and reduce it to an intelligent, transparent, and proactive management space. The framework enhances the transparency on construction development, risk changes and safety delivery and also allows stakeholders to know the logic behind automated notifications and suggestions. Such interpretability strengthens trust, accountability, and informed decision-making across multidisciplinary project teams.

The results of the implementation show that the use of the AI intelligence with visualization dash boards leads to the improvement of accuracy and speed of monitoring, as well as to the improvement of coordinating operations. The research affirms that the efficient planning of resources, the mitigation of delays, and compliance tracking of complex civil infrastructure projects can be supported using data-driven digital twins.

Future research can be aimed at incorporating real-time streams of IoT sensors, drones site imaging, and computer vision analytics to add additional

value to the live project data feeds. Moreover, the framework can be extended with federated learning, edge computing, and cross-project benchmarking models to enhance scalability and acceptance of the framework in the industry. Generalizability and performance standardization will also be enhanced by longitudinal validation of a number of construction typologies.

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